

Connecting Wireless Sensor Networks to the Internet - a 6lowpan Implementation for TinyOS 2.0

Matúš Harvan

Jacobs University Bremen
Bremen, Germany

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Outline

- 1 Introduction
 - TelosB and MicaZ Hardware Platforms
 - IEEE 802.15.4 (PHY and MAC layer)
 - TinyOS and nesC
 - 6lowpan
- 2 Implementation
 - Buffers
 - Fragments
 - 6lowpan for Linux
 - Missing Features
- 3 Demonstration
- 4 Conclusion
 - Evaluation

Wireless Sensor Networks

Definition

A wireless sensor network (WSN) is a **wireless network** consisting of **spatially distributed autonomous devices** using **sensors** to **cooperatively monitor** physical or environmental conditions, such as temperature, sound, vibration, pressure, motion or pollutants.

- Small computers with a wireless interface
- Smart alternatives to dumb RFID tags

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TelosB Hardware Platform

TI MSP430 MCU

- 16 bit RISC at 8 MHz
- 16 registers
- 10kB RAM
- 48kB Flash
- 16kB EEPROM



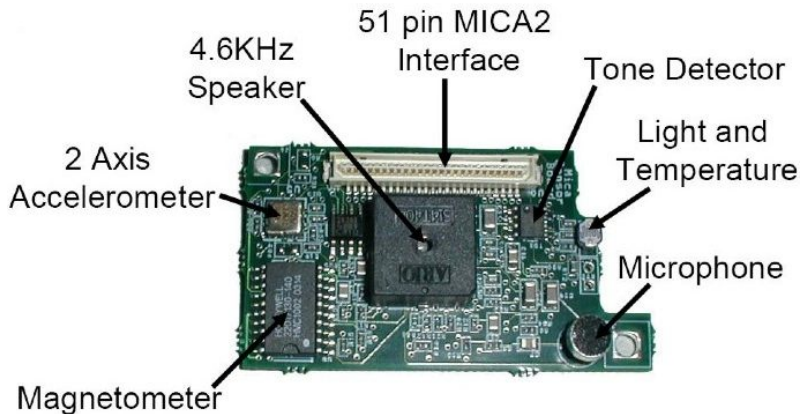
MicaZ Hardware Platforms

Atmel AVR
ATmega 128

- 8 bit RISC
- 32 registers
- 4kB RAM
- 128kB Flash
- 4kB EEPROM



Mica Sensor Board MTS310



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Radio – IEEE 802.15.4

IEEE 802.15.4

- 250 kbps (16 channels, 2.4 GHz ISM band)
- personal area networks (10 meters range)
- PHY and MAC layer covered
- Link encryption (AES) (no key management)
- Full / Reduced function devices

ChipCon CC2420

- popular 802.15.4 air interface
- 128byte TX/RX buffer
- used on the TelosB and MicaZ motes

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- embedded operating system for WSN motes
- written in the *nesC* language
- event-driven architecture
- no kernel/user space differentiation
- single shared stack
- static memory allocation only (no malloc/free)
- no process or memory management
- components statically linked together

nesC: Programming Language for Embedded Systems

- Programming language:
 - a dialect/extension of C
 - static memory allocation only (no malloc/free)
 - whole-program analysis, efficient optimization
 - race condition detection
- Implementation:
 - pre-processor – output is a C-program, that is compiled using gcc for the specific platform
 - statically linking functions
- For more details, see [3]

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6lowpan – IPv6 over 802.15.4

- IETF working group (IPv6 over low-power wireless personal area networks)
- 6lowpan header/dispatch value before the IP header

layer 2 header (802.15.4)
optional Mesh Addressing Header (6lowpan)
optional Broadcast Header (6lowpan)
optional Fragmentation Header (6lowpan)
IPv6 header (6lowpan-compressed)
layer 4 header (i.e. 6lowpan compressed UDP header)
layer 4/application payload

Table: 802.15.4 frame with 6lowpan payload

6lowpan – Details

- header compression
 - IPv6 and UDP headers can ideally be compressed from $40 + 8$ to $2 + 4$ bytes
 - no prior communication for context establishment necessary
- fragmentation below the IP layer
 - IPv6 requires a minimum MTU of 1280 bytes, but 802.15.4 can at best provide 102 bytes
 - Fragmentation Header
- mesh networking support
 - Mesh Addressing Header and Broadcast Header
 - routing algorithms and further details out of scope of the 6lowpan working group

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Design principles

- run on the TelosB and MicaZ motes
 - fit into 4KB of RAM
- easily readable and maintainable code preferred over optimizing to squeeze into the least possible amount of memory

Modules and interfaces

- `IPC.nc` – configuration, used by the application
- `IPP.nc` – module with the implementation
- `UDPCClient.nc` – interface used by the application
- `IP.h` – included by the application
- `IP_internal.h` – used only by `IPC` and `IPP`

UDPClient interface

UDPClient

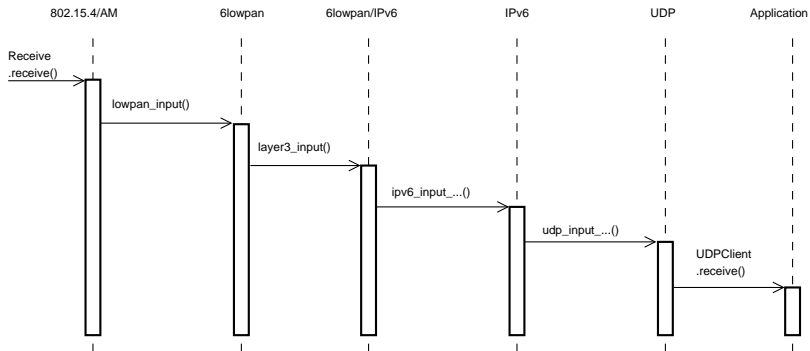
```
interface UDPClient {
    command error_t listen( uint16_t port );

    command error_t connect(const ip6_addr_t *addr, const uint16_t port);

    command error_t sendTo(const ip6_addr_t *addr, uint16_t port,
                           const uint8_t *buf, uint16_t len);
    command error_t send(const uint8_t *buf, uint16_t len);
    event void sendDone(error_t result, void* buf);

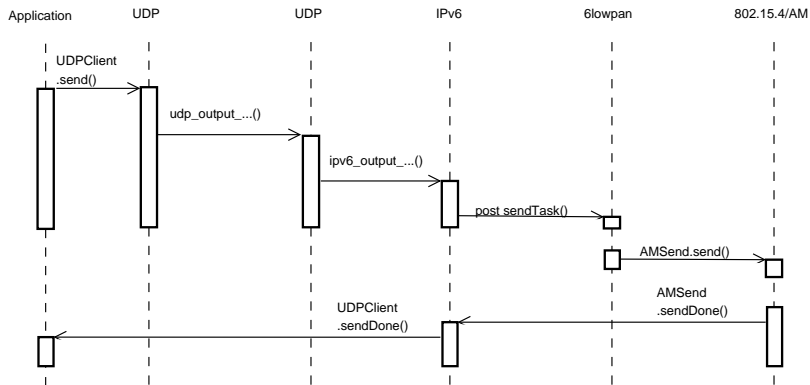
    event void receive(const ip6_addr_t *addr, uint16_t port,
                       uint8_t *buf, uint16_t len);
}
```

Receiving a UDP packet



- each network layer and protocol handled by a separate function

Sending a UDP packet



- again separate functions
- task for sending packets
- queue of outgoing packets

Sending – Why a task and queuing?

- may have to determine destination's link-layer address (Neighbor Discovery)
 - before sending the packet
 - need to know where to send the packet
 - before HC1-encoding the IPv6 header
- fragmentation may be needed
- receive frames while fragments are being sent

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Buffers – Design goals

- accommodate for both
 - short unfragmented packet – up to 102 bytes
 - large fragmented packet – up to 1280 bytes
- higher-layer (UDP) payload buffer provided by the application
- need to prepend headers

Buffers – Design

- all headers together are certainly not larger than an unfragmented packet
- use the same buffer for headers as for the unfragmented packet payload

size	header
<hr/>	
<i>6lowpan optional headers</i>	
5 – 19	mesh addressing
2	broadcast
4 – 5	fragmentation
<hr/>	
<i>layer 3 header</i>	
41	IPv6 (uncompressed)
3 – 41	IPv6 (HC1-compressed)
<hr/>	
<i>layer 4 headers</i>	
8	UDP (uncompressed)
4 – 9	UDP (HC_UDP-compressed)
8	ICMP
24	TCP

Buffers - representing a packet

lowpan_pkt_t

```
typedef struct _lowpan_pkt_t {
    /* buffers */
    uint8_t *app_data;          /* buffer for application data */
    uint16_t app_data_len;     /* how much data is in the buffer */
    uint8_t *app_data_begin;   /* start of the data in the buffer */
    uint8_t app_data_dealloc;  /* shall IPC deallocate the app_data buffer? */

    uint8_t header[LINK_DATA_MTU]; /* buffer for the header (tx)
                                     * or unfragmented 802.15.4 frame (rx) */
    uint16_t header_len;      /* how much data is in the buffer */
    uint8_t *header_begin;   /* start of the data in the buffer */

    /* fragmentation (tx) */
    uint16_t dgram_tag;
    uint16_t dgram_size;
    uint8_t dgram_offset;    /* offset where next fragment starts (tx) */

    /* IP addresses */
    ip6_addr_t ip_src_addr;
    ip6_addr_t ip_dst_addr;

    /* 802.15.4 addresses */
    hw_addr_t hw_src_addr;
    hw_addr_t hw_dst_addr;

    uint8_t notify_num;      /* num of UDPClients + 1
                               * 0 for no sendDone notification */

    struct _lowpan_pkt_t *next;
} lowpan_pkt_t;
```

Buffers – changing the owner

- `app_data_dealloc` allows to change the “owner” of the `app_data` buffer
- used when replying to an ICMP echo request to prevent copying of data
- might be useful for `UDPCli` as well

Buffers - receiving a packet

- one global buffer for received packet
- unfragmented packets fit into header buffer
- fragmented packets in app_data buffer (provided by fragment reassembly)
- no concurrency – processing of the received packet cannot be interrupted by receiving another packet (until control is returned back to TinyOS)

Buffers - sending a packet

- SendPktPool
 - pool of `lowpan_pkt_t` packets for sending
 - compile-time configurable size – allows to make use of extra memory on the TelosB mote
- outgoing packets queued, queue processed by `sendTask`

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Fragmentation

- dealt with in `sendTask`

Fragment reassembly

- reassembled into an `app_data` buffer
- pool of `app_data` buffers – `AppDataPool`
 - compile-time configurable size
 - size determines how many packets can be reassembled concurrently
- when reassembly completed, `app_data` buffer moved into the global `lowpan_pkt_t` for receiving

Fragment reassembly

- two options for keeping track of received fragments
 - 1 bitmap – 160 bits = 20 bytes would do
 - 2 linked list
- 6lowpan draft requires treating overlapping fragments differently if offset or length differ
- need a linked list to determine if offset or length differ or the fragment is just a duplicate
- linked list items also managed by a pool
- if full size of 802.15.4 frames is used, 15 fragments are sufficient for a 1280-byte packet

Link-layer

- TinyOS 2.0 does not have a proper 802.15.4 stack
- TinyOS notion of networking: *Active Messages*
- Active Message header same as 802.15.4 data frame header
 - additional 1-byte AM Type field in the 802.15.4 payload



- solution: sending 6lowpan payload as Active Message payload

IPv6 Addresses

- one global IPv6 address (prefix currently hardcoded)
- one link-local IPv6 address
- interface identifier computed from Active Message address (802.15.4 short address) of the mote
- the application cannot change the IPv6 addresses (for now)

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serial_tun daemon – 6lowpan for Linux

- allows a Linux PC to use a mote as an 802.15.4 interface
 - the mote runs the BaseStationCC2420 application to forward frames between the USB and the radio interface
- 6lowpan en- and decapsulation
 - the Linux kernel does not speak 6lowpan
- tun interface
 - proper network interface, `ifconfig`-supported
 - packets further handled by the Linux kernel

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Missing features

- proper 802.15.4 stack – tunneling as Active Message payload
- HC1 encoding – non-zero Traffic Class and Flow Label
- HC_UDP encoding – compressed UDP port numbers
- fragmentation PC → mote not yet 100% reliable
 - some fragments not received by the mote
 - workaround with sleeping before sending a subsequent fragment

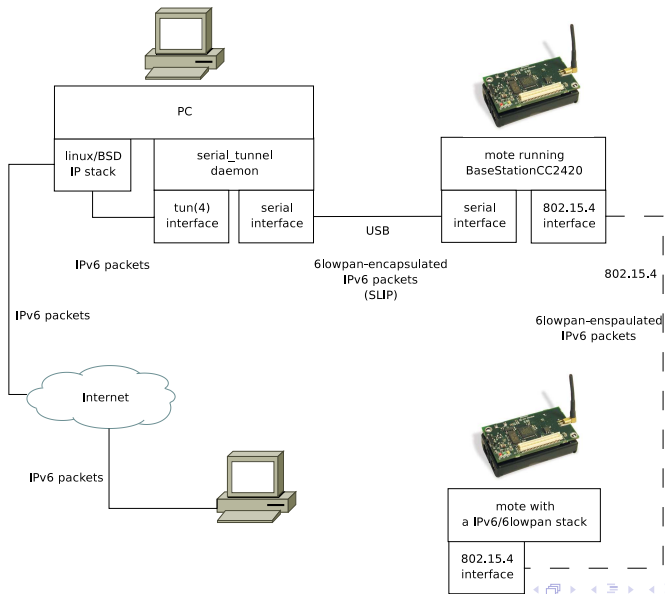
Missing features

- Neighbor Discovery
 - using link-layer broadcast instead
 - unclear which parts actually needed, under discussion in 6lowpan and RSN groups
- IPv6 extension header, IPv6 fragmentation
- sending ICMP error message

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6lowpan demonstration



6lowpan – Demonstration

- ping – IPv6
 - unfragmented
 - fragmented
- cli – telnet over IPv6/UDP
 - control the leds
 - control the sounder
 - request UDP data to be sent back
 - unfragmented
 - fragmented

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Evaluation

- 21900 bytes of ROM, 2906 bytes of RAM
- ping works
- UDP works
- fragmentation works
- tested against Linux ping6 and nc6
- robust – ping can run for several hours
- the design allows to easily add
 - replying to Neighbor Solicitations
 - sending Neighbor Solicitations before HC1-encoding or sending a packet
 - TCP protocol

References



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The Design Space of Wireless Sensor Networks
[IEEE Wireless Communications 11\(6\), December 2004.](#)



J. Polastre, R. Szewczyk and David Culler.

Telos: Enabling Ultra-Low Power Wireless Research
[IEEE IPSN, April 2005.](#)



D. Gay, P. Levis, R. von Behren, M. Welsh, E. Brewer and D. Culler.

The nesC Language: A Holistic Approach to Networked Embedded Systems
[ACM PLDI, June 2003.](#)



G. Montenegro, N. Kushalnagar, J. Hui and D. Culler.

Transmission of IPv6 Packets over IEEE 802.14.4 Networks
[Internet-Draft draft-ietf-6lowpan-format-13 \(work in progress\), April 2007.](#)

Questions?

Implementation: `http://www.eecs.iu-bremen.de/users/harvan/files/6lowpan.tar.gz`

Backup slides

Applications

- Environmental monitoring
- Seismic detection
- Disaster situation monitoring and recovery
- Health and medical monitoring
- Inventory tracking and logistics
- Smart spaces (home/office scenarios)
- Military surveillance

Why connect WSNs to the Internet?

- Internet Protocol (IP)
 - ubiquitous
 - de-facto standard
 - already deployed
 - plethora of applications available

Design Goals

- cheap
 - ideally less than 1 Euro
- many
 - lots of devices, economies of scale
- robust
 - unattended operation (no repair)
- small
 - importance depends on the circumstances
- low-power
 - difficult/impossible to replace batteries

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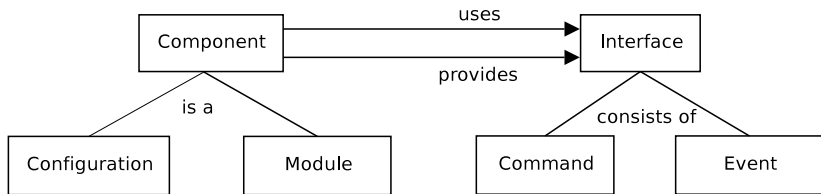
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TinyOS – Functionality

- hardware abstraction
- access to sensors
- access to actuators
- scheduler (tasks, hardware interrupts)
- timer
- radio interface
- Active Messages (networking)
- storage (using flash memory on the motes)
- ...

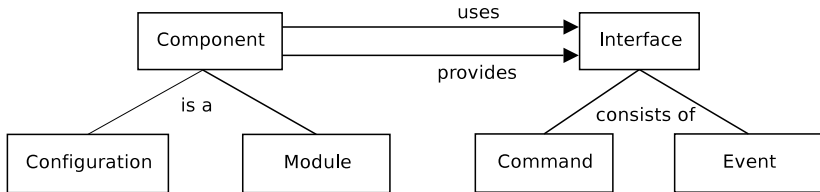
nesC – Components and Interfaces

- a nesC application consists of *components*
 - *modules* – implement interfaces
 - *configurations* – connect modules together via their interfaces (*wiring*)
- components provide and use *interfaces*
 - *commands* – can be called by other modules
 - *events* – signaled by other modules



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NesC — Concurrency — Tasks

Define a Task

```
task void task_name() { ... }
```

Post a Task

```
post task_name();
```

- posting a task – the task is placed on an internal task queue which is processed in FIFO order
- a task runs to completion before the next task is run, i.e. tasks do not preempt each other
- tasks can be preempted by hardware events